Third-Party Notices

Microsoft Edge for Android

Last update: August 3, 2021

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Android adaptation and tweak by Jim Huang <jserv@0xlab.org>.

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Emulation of getentropy(2) as documented at: <http://www.openbsd.org/cgi-bin/man.cgi/OpenBSD-current/man2/getentropy.2>

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Theo de Raadt <deraadt@openbsd.org> came up with the idea of using such a mathematical system to generate more random (yet non-repeating) ids to solve the resolver/named problem. But Niels designed the actual system based on the constraints.

Later modified by Damien Miller to wrap the LCG output in a 15-bit permutation generator based on a Luby-Rackoff block cipher. This ensures the output is non-repeating and preserves the MSB twiddle trick, but makes it more resistant to LCG prediction.

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## Android Robot image

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## Asm

ASM: a very small and fast Java bytecode manipulation framework

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<https://github.com/google/benchmark/tree/95a1435b8171f7e781fe0465bff8146609a488c1>

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Extracted from mac/include/DeckLinkAPI.h:

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## Breakpad, An open-source multi-platform crash reporting system v8.00

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## Chrome Custom Tabs - Example and Usage

<https://chromium.googlesource.com/external/github.com/GoogleChrome/custom-tabs-client>

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## Cognitive-Speech-STT-Windows version 1.2.2

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## Compact Encoding Detection

Compact Encoding Detection v2f40a850bcc5d6f7c1bfa02dbf42ad19d8220dc0

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<https://github.com/CLD2Owners/cld2>

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## CRC32C

<https://github.com/google/crc32c>

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## dom-distiller-js

**dom-distiller-js v489c6609cb**

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## enum34

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- libpostproc
- optional x86 optimization in the files
  - `libavcodec/x86/flac\_dsp\_gpl.asm`
  - `libavcodec/x86/idct\_mmx.c`
  - `libavfilter/x86/vf\_removegrain.asm`
- the following building and testing tools
  - `compat/solaris/make\_sunver.pl`
  - `doc/t2h.pm`
  - `doc/texi2pod.pl`
  - `libswresample/swresample-test.c`
  - `tests/checkasm/\*`
  - `tests/tiny\_ssim.c`
- the following filters in libavfilter:
  - `vf\_blackframe.c`
  - `vf\_boxblur.c`
  - `vf\_colormatrix.c`
  - `vf\_cover\_rect.c`
  - `vf\_cropdetect.c`
  - `vf\_delogo.c`
  - `vf\_eq.c`
  - `vf\_find\_rect.c`
  - `vf\_fspp.c`
  - `vf\_geq.c`
  - `vf\_histeq.c`
  - `vf\_hqdn3d.c`
  - `vf\_interlace.c`
  - `vf\_kerndeint.c`
  - `vf\_mcdeint.c`
  - `vf\_mpdecimate.c`
  - `vf\_owdenoise.c`
  - `vf\_perspective.c`
  - `vf\_phase.c`
  - `vf\_pp.c`
  - `vf\_pp7.c`
  - `vf\_pullup.c`
  - `vf\_repeatfields.c`
  - `vf\_sab.c`
  - `vf\_smartblur.c`
  - `vf\_spp.c`
  - `vf\_stereo3d.c`
  - `vf\_super2xsai.c`
  - `vf\_tinterlace.c`
  - `vf\_uspp.c`
  - `vsrc\_mptestsrc.c`

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- frei0r
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- librubberband
- libvidstab
- libx264
- libx265
- libxavs
- libxvid

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ACM's Hybrid Open Access Publishing Program began in April 2013. Starting in 2014, ACM will distribute all hybrid OA revenue to its academic institutional subscriber base.

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The Hybrid Open Access Model has existed for a number of years, though different publishers and societies choose to implement it in different ways. Many feel that Hybrid Open Access options are a step in the right direction in making the scholarly literature more openly accessible. But there is also concern that some publishers may unfairly take advantage of such a model for their own financial gain by using open access fees to supplement their existing subscription revenue streams, rather than use them responsibly to address the growing concern over funding in the library environment.

The practice of enhancing net revenues by retaining OA fees for content that is also paid for by subscription has been dubbed "double-dipping".

In developing ACM's Hybrid Open Access model, much consideration was given to concerns raised about this perceived "double-dipping" by some publishers.

As one of the world's leading scientific societies, ACM is committed to publishing policies that advance the goals of scientific discovery, innovation, and education in a sustainable and responsible way. ACM's Hybrid Open Access Program is therefore being implemented in a highly transparent, affordable, and fair way for the mutual benefit of all stakeholders in the scholarly community.

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## glog

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## Google fork of Khronos reference front-end for GLSL and ESSL v2016.5.13

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## Google Toolbox for Mac v626

<https://github.com/google/google-toolbox-for-mac>

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## googletest/googlemock

<https://github.com/google/googletest/tree/d175c8bf823e709d570772b038757fadf63bc632/googlemock>

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## googletest/googletest/

<https://github.com/google/googletest/tree/d175c8bf823e709d570772b038757fadf63bc632/googletest>

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## gRPC, an RPC library and framework

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<https://github.com/googlei18n/libphonenumber/>

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## libjingle XMPP and xmllite libraries

**libjingle XMPP and xmllite libraries v5493b8a59deb16cf0481e24707a0ed72d19047dc**

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## libjpeg v6b

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<https://github.com/google/libprotobuf-mutator>

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\* Version 1.3 -- 17-Mar-2006
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## newlib-extras v2.0.0

ftp://sourceware.org/pub/newlib/newlib-2.0.0.tar.gz

README for newlib-2.0.0 release
(mostly cribbed from the README in the gdb-4.13 release)

This is `newlib', a simple ANSI C library, math library, and collection of board support packages.

The newlib and libgloss subdirectories are a collection of software from several sources, each wi6h their own copyright and license. See the file COPYING.NEWLIB for details. The rest of the release tree is under either the GNU GPL or LGPL licenses.

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Unpacking and Installation -- quick overview
==========================

When you unpack the newlib-2.0.0.tar.gz file, you'll find a directory called `newlib-2.0.0', which contains:

COPYING          config/          install-sh\*      mpw-configure
COPYING.LIB      config-ml.in     libgloss/         mpw-install
COPYING.NEWLIB   config.guess\*    mkinstalldirs\*   newlib/
CYGNUS           config.sub\*      move-if-change\*  symlink-tree\*
ChangeLog        configure\*       mpw-README       texinfo/
Makefile.in      configure.in     mpw-build.in
README           etc/             mpw-config.in

To build NEWLIB, you must follow the instructions in the section entitled "Compiling NEWLIB".

This will configure and build all the libraries and crt0 (if one exists). If `configure' can't determine your host system type, specify one as its argument, e.g., sun4 or sun4sol2. NEWLIB is most often used in cross environments.

NOTE THAT YOU MUST HAVE ALREADY BUILT AND INSTALLED GCC and BINUTILS.

More Documentation
==================

Newlib documentation is available on the net via:
<http://sourceware.org/newlib/docs.html>

All the documentation for NEWLIB comes as part of the machine-readable distribution. The documentation is written in Texinfo format, which is a documentation system that uses a single source file to produce both on-line information and a printed manual. You can use one of the Info formatting commands to create the on-line version of the documentation and TeX (or `texi2roff') to typeset the printed version.

If you want to format these Info files yourself, you need one of the Info formatting programs, such as `texinfo-format-buffer' or `makeinfo'.

If you want to typeset and print copies of this manual, you need TeX, a program to print its DVI output files, and `texinfo.tex', the Texinfo definitions file.

TeX is a typesetting program; it does not print files directly, but produces output files called DVI files. To print a typeset document, you need a program to print DVI files. If your system has TeX installed, chances are it has such a program. The precise command to use depends on your system; `lpr -d' is common; another (for PostScript devices) is `dvips'. The DVI print command may require a file name without any extension or a `.dvi' extension.

TeX also requires a macro definitions file called `texinfo.tex'. This file tells TeX how to typeset a document written in Texinfo format. On its own, TeX cannot read, much less typeset a Texinfo file. `texinfo.tex' is distributed with NEWLIB and is located in the `newlib-VERSION-NUMBER/texinfo' directory.

Compiling NEWLIB
================

To compile NEWLIB, you must build it in a directory separate from the source directory. If you want to run NEWLIB versions for several host or target machines, you need a different `newlib' compiled for each combination of host and target. `configure' is designed to make this easy by allowing you to generate each configuration in a separate subdirectory. If your `make' program handles the `VPATH' feature correctly (like GNU `make') running `make' in each of these directories builds the `newlib' libraries specified there.

To build `newlib' in a specific directory, run `configure' with the `--srcdir' option to specify where to find the source. (You also need to specify a path to find `configure' itself from your working directory. If the path to `configure' would be the same as the argument to `--srcdir', you can leave out the `--srcdir' option; it will be assumed.)

For example, with version 2.0.0, you can build NEWLIB in a separate directory for a Sun 4 cross m68k-aout environment like this:

cd newlib-2.0.0
mkdir ../newlib-m68k-aout
cd ../newlib-m68k-aout
../newlib-2.0.0/configure --host=sun4 --target=m68k-aout make

When `configure' builds a configuration using a remote source directory, it creates a tree for the binaries with the same structure (and using the same names) as the tree under the source directory. In the example, you'd find the Sun 4 library `libiberty.a' in the directory `newlib-m68k-aout/libiberty', and NEWLIB itself in `newlib-m68k-aout/newlib'.

When you run `make' to build a program or library, you must run it in a configured directory--whatever directory you were in when you called `configure' (or one of its subdirectories).

The `Makefile' that `configure' generates in each source directory also runs recursively. If you type `make' in a source directory such as `newlib-2.0.0' (or in a separate configured directory configured with `--srcdir=PATH/newlib-2.0.0'), you will build all the required libraries.

When you have multiple hosts or targets configured in separate directories, you can run `make' on them in parallel (for example, if they are NFS-mounted on each of the hosts); they will not interfere with each other.

Specifying names for hosts and targets
======================================

The specifications used for hosts and targets in the `configure' script are based on a three-part naming scheme, but some short predefined aliases are also supported. The full naming scheme encodes three pieces of information in the following pattern:

ARCHITECTURE-VENDOR-OS

For example, you can use the alias `sun4' as a HOST argument or in a `--target=TARGET' option. The equivalent full name is `sparc-sun-sunos4'.

The `configure' script accompanying NEWLIB does not provide any query facility to list all supported host and target names or aliases. `configure' calls the Bourne shell script `config.sub' to map abbreviations to full names; you can read the script, if you wish, or you can use it to test your guesses on abbreviations--for example:

% sh config.sub sun4
sparc-sun-sunos4.1.1
% sh config.sub sun3
m68k-sun-sunos4.1.1
% sh config.sub decstation
mips-dec-ultrix4.2
% sh config.sub hp300bsd
m68k-hp-bsd
% sh config.sub i386v
i386-pc-sysv
% sh config.sub i786v
Invalid configuration `i786v': machine `i786v' not recognized

The Build, Host and Target Concepts in newlib
=============================================

The build, host and target concepts are defined for gcc as follows:

build: the platform on which gcc is built.
host: the platform on which gcc is run.
target: the platform for which gcc generates code.

Since newlib is a library, the target concept does not apply to it, and the build, host, and target options given to the top-level configure script must be changed for newlib's use.

The options are shifted according to these correspondences:

gcc's build platform has no equivalent in newlib.
gcc's host platform is newlib's build platform.
gcc's target platform is newlib's host platform.
and as mentioned before, newlib has no concept of target.

`configure' options
===================

Here is a summary of the `configure' options and arguments that are most often useful for building NEWLIB. `configure' also has several other options not listed here.

configure [--help]
[--prefix=DIR]
[--srcdir=PATH]
[--target=TARGET] HOST

You may introduce options with a single `-' rather than `--' if you prefer; but you may abbreviate option names if you use `--'.

`--help'
Display a quick summary of how to invoke `configure'.

`--prefix=DIR'
Configure the source to install programs and files in directory `DIR'.

`--exec-prefix=DIR'
Configure the source to install host-dependent files in directory `DIR'.

`--srcdir=PATH'
\*Warning: using this option requires GNU `make', or another `make' that compatibly implements the `VPATH' feature. Use this option to make configurations in directories separate from the NEWLIB source directories. Among other things, you can use this to build (or maintain) several configurations simultaneously, in separate directories. `configure' writes configuration specific files in the current directory, but arranges for them to use the source in the directory PATH. `configure' will create directories under the working directory in parallel to the source directories below PATH.

`--norecursion'
Configure only the directory level where `configure' is executed; do not propagate configuration to subdirectories.

`--target=TARGET'
Configure NEWLIB for running on the specified TARGET.

There is no convenient way to generate a list of all available targets.

`HOST ...'
Configure NEWLIB to be built using a cross compiler running on the specified HOST.

There is no convenient way to generate a list of all available hosts.

To fit diverse usage models, NEWLIB supports a group of configuration options so that library features can be turned on/off according to target system's requirements.

One feature can be enabled by specifying `--enable-FEATURE=yes' or `--enable-FEATURE'. Or it can be disable by `--enable-FEATURE=no' or `--disable-FEATURE'.

`--enable-newlib-io-pos-args'
Enable printf-family positional arg support.
Disabled by default, but some hosts enable it in configure.host.

`--enable-newlib-io-c99-formats'
Enable C99 support in IO functions like printf/scanf.
Disabled by default, but some hosts enable it in configure.host.

`--enable-newlib-register-fini'
Enable finalization function registration using atexit.
Disabled by default.

`--enable-newlib-io-long-long'
Enable long long type support in IO functions like printf/scanf.
Disabled by default, but many hosts enable it in configure.host.

`--enable-newlib-io-long-double'
Enable long double type support in IO functions printf/scanf.
Disabled by default, but some hosts enable it in configure.host.

`--enable-newlib-mb'
Enable multibyte support.
Disabled by default.

`--enable-newlib-iconv-encodings'
Enable specific comma-separated list of bidirectional iconv encodings to be built-in.
Disabled by default.

`--enable-newlib-iconv-from-encodings'
Enable specific comma-separated list of \"from\" iconv encodings to be built-in.
Disabled by default.

`--enable-newlib-iconv-to-encodings'
Enable specific comma-separated list of \"to\" iconv encodings to be built-in.
Disabled by default.

`--enable-newlib-iconv-external-ccs'
Enable capabilities to load external CCS files for iconv.
Disabled by default.

`--disable-newlib-atexit-dynamic-alloc'
Disable dynamic allocation of atexit entries.
Most hosts and targets have it enabled in configure.host.

`--enable-newlib-reent-small'
Enable small reentrant struct support.
Disabled by default.

`--disable-newlib-fvwrite-in-streamio'
NEWLIB implements the vector buffer mechanism to support stream IO buffering required by C standard. This feature is possibly unnecessary for embedded systems which won't change file buffering with functions like `setbuf' or `setvbuf'. The buffering mechanism still acts as default for STDIN/STDOUT/STDERR even if this option is specified.
Enabled by default.

`--disable-newlib-fseek-optimization'
Disable fseek optimization. It can decrease code size of application calling `fseek`.
Enabled by default.

`--disable-newlib-wide-orient'
C99 states that each stream has an orientation, wide or byte. This feature is possibly unnecessary for embedded systems which only do byte input/output operations on stream. It can decrease code size by disable the feature.
Enabled by default.

`--enable-newlib-nano-malloc'
NEWLIB has two implementations of malloc family's functions, one in `mallocr.c' and the other one in `nano-mallocr.c'. This options enables the nano-malloc implementation, which is for small systems with very limited memory. Note that this implementation does not support `--enable-malloc-debugging' any more.
Disabled by default.

`--disable-newlib-unbuf-stream-opt'
NEWLIB does optimization when `fprintf to write only unbuffered unix file'. It creates a temorary buffer to do the optimization that increases stack consumption by about `BUFSIZ' bytes. This option disables the optimization and saves size of text and stack.
Enabled by default.

`--enable-multilib'
Build many library versions.
Enabled by default.

`--enable-target-optspace'
Optimize for space.
Disabled by default.

`--enable-malloc-debugging'
Indicate malloc debugging requested.
Disabled by default.

`--enable-newlib-multithread'
Enable support for multiple threads.
Enabled by default.

`--enable-newlib-iconv'
Enable iconv library support.
Disabled by default.

`--enable-newlib-elix-level'
Supply desired elix library level (1-4). Please refer to HOWTO for more information about this option.
Set to level 0 by default.

`--disable-newlib-io-float'
Disable printf/scanf family float support.
Enabled by default.

`--disable-newlib-supplied-syscalls'
Disable newlib from supplying syscalls.
Enabled by default.

`--enable-lite-exit'
Enable lite exit, a size-reduced implementation of exit that doesn't invoke clean-up functions such as \_fini or global destructors.
Disabled by default.

Running the Testsuite
=====================

To run newlib's testsuite, you'll need a site.exp in your home directory which points dejagnu to the proper baseboards directory and the proper exp file for your target.

Before running make check-target-newlib, set the DEJAGNU environment variable to point to ~/site.exp.

Here is a sample site.exp:

# Make sure we look in the right place for the board description files.
if ![info exists boards\_dir] {
    set boards\_dir {}
}
lappend boards\_dir "your dejagnu/baseboards here"

verbose "Global Config File: target\_triplet is $target\_triplet" 2

global target\_list
case "$target\_triplet" in {

    { "mips-\*elf\*" } {
        set target\_list "mips-sim"
    }

    default {
        set target\_list { "unix" }
    }
}

mips-sim refers to an exp file in the baseboards directory. You'll need to add the other targets you're testing to the case statement.

Now type make check-target-newlib in the top-level build directory to run the testsuite.

Shared newlib
=============

newlib uses libtool when it is being compiled natively (with --target=i[34567]86-pc-linux-gnu) on an i[34567]86-pc-linux-gnu host. This allows newlib to be compiled as a shared library.

To configure newlib, do the following from your build directory:

$(source\_dir)/src/configure --with-newlib --prefix=$(install\_dir)

configure will recognize that host == target == i[34567]86-pc-linux-gnu, so it will tell newlib to compile itself using libtool. By default, libtool will build shared and static versions of newlib.

To compile a program against shared newlib, do the following (where target\_install\_dir = $(install\_dir)/i[34567]86-pc-linux-gnu):

gcc -nostdlib $(target\_install\_dir)/lib/crt0.o progname.c -I $(target\_install\_dir)/include -L $(target\_install\_dir)/lib -lc -lm -lgcc

To run the program, make sure that $(target\_install\_dir)/lib is listed in the LD\_LIBRARY\_PATH environment variable.

To create a static binary linked against newlib, do the following:

gcc -nostdlib -static $(target\_install\_dir)/lib/crt0.o progname.c -I $(target\_install\_dir)/include -L $(target\_install\_dir)/lib -lc -lm

libtool can be instructed to produce only static libraries. To build newlib as a static library only, do the following from your build directory:

$(source\_dir)/src/configure --with-newlib --prefix=$(install\_dir) --disable-shared

Regenerating Configuration Files
================================

At times you will need to make changes to configure.in and Makefile.am files. This will mean that configure and Makefile.in files will need to be regenerated.

At the top level of newlib is the file: acinclude.m4. This file contains the definition of the NEWLIB\_CONFIGURE macro which is used by all configure.in files in newlib. You will notice that each directory in newlib containing a configure.in file also contains an aclocal.m4 file. This file is generated by issuing: aclocal -I${relative\_path\_to\_toplevel\_newlib\_dir} -I${relative\_path\_to\_toplevel\_src\_dir}
The first relative directory is to access acinclude.m4. The second relative directory is to access libtool information in the top-level src directory.

For example, to regenerate aclocal.m4 in newlib/libc/machine/arm:

aclocal -I ../../.. -I ../../../..

Note that if the top level acinclude.m4 is altered, every aclocal.m4 file in newlib should be regenerated.

If the aclocal.m4 file is regenerated due to a change in acinclude.m4 or if a configure.in file is modified, the corresponding configure file in the directory must be regenerated using autoconf. No parameters are necessary. In the previous example, we would issue:

autoconf

from the newlib/libc/machine/arm directory.

If you have regenerated a configure file or if you have modified a Makefile.am file, you will need to regenerate the appropriate Makefile.in file(s). For newlib, automake is a bit trickier. First of all, all Makefile.in files in newlib (and libgloss) are generated using the --cygnus option of automake.

Makefile.in files are generated from the nearest directory up the chain which contains a configure.in file. In most cases, this is the same directory containing configure.in, but there are exceptions. For example, the newlib/libc directory has a number of subdirectories that do not contain their own configure.in files (e.g. stdio). For these directories, you must issue the automake command from newlib/libc which is the nearest parent directory that contains a configure.in. When you issue the automake command, you specify the subdirectory for the Makefile.in you are regenerating. For example:

automake --cygnus stdio/Makefile stdlib/Makefile

Note how multiple Makefile.in files can be created in the same step. You would not specify machine/Makefile or sys/Makefile in the previous example because both of these subdirectories contain their own configure.in files. One would change to each of these subdirectories and in turn issue:

automake --cygnus Makefile

Let's say you create a new machine directory XXXX off of newlib/libc/machine. After creating a new configure.in and Makefile.am file, you would issue:

aclocal -I ../../..
autoconf
automake --cygnus Makefile

from newlib/libc/machine/XXXX

It is strongly advised that you use an adequate version of autotools. For this latest release, the following were used: autoconf 2.68, aclocal 1.11.6, and automake 1.11.6.

Reporting Bugs
==============

The correct address for reporting bugs found in NEWLIB is "newlib@sourceware.org". Please email all bug reports to that address. Please include the NEWLIB version number (e.g., newlib-2.0.0), and how you configured it (e.g., "sun4 host and m68k-aout target"). Since NEWLIB supports many different configurations, it is important that you be precise about this.

Archives of the newlib mailing list are on-line, see
<http://sourceware.org/ml/newlib/>

## nimbus-jose-jwt

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## Nmoinvaz/minizip

<https://github.com/nmoinvaz/minizip>

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## OpenVR SDK

<https://github.com/ValveSoftware/openvr>

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qcms
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## Readium-shared-js.

<https://github.com/readium/readium-shared-js/>

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## Snappy: A fast compressor/decompressor v1.1.0-updates

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## WebM container parser and writer.

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## Windows Template Library (WTL) v8.0

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## woff2

**woff2 va15a8ab86b934cf436f8fac4a8a11ddf8b59d792**

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## XCDFormInputAccessoryView

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## xdg-mime

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## xdg-user-dirs

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## xdg-utils

**xdg-utils v3ba869a97b737fd308502a7f9e63bda202891642**

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## Yara

<https://github.com/virustotal/yara>

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## zlib v1.2.11

version 1.2.11, January 15th, 2017

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